

HPM Series MODBUS Communication Protocol

Note: The hexadecimal numbers are expressed by 'XXXXH' or 'XXH' in the below description.

1. MODBUS-RTU Standard Communication Format

This communication use MODBUS RTU mode, message frame as below:

| Slave address | Function code | Data area | CRC Check (Cyclic Redundancy Check) | |
|---------------|---------------|----------------------|-------------------------------------|----------|
| 1 Byte | 1 Byte | 0 or up to 252 bytes | 2 Bytes | |
| | | | CRC low | CRC high |

(1)**Slave address:** Host controls peristaltic pump address number. The pump address number should not be same when they are in the same 485 line. The address number range is 1~32, 0 means broadcast.

(2)**Function code:** The protocol use 2 common function codes which defined by MODBUS protocol.

03H: Read the contents of holding register

06H: Write a word to the holding register

10H: Write a long type to the holding register

Data zone: Specific information instructions that the peristaltic pump needs to execute, such as start/stop, direction, accelerate/decelerate etc.

(3)**CRC check:** CRC code is 2 bytes, 16 check codes. Use CRC-16 (which used in American binary synchronous system).

Polynomial: $G(X)=X^{16}+X^{15}+X^2+1$.

CRC check C language code please refer to Appendix 1.

Frame format for transmission of each function code

03 function code:

Request:

| | | |
|---------------------|---------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | 0x03 |
| Start address | 2 bytes | 0x0000-0xFFFF |
| Number of registers | 2 bytes | 1-125 (0x7D) |
| CRC check | 2 bytes | |

Respond

| | | |
|-----------------|------------------------------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | 0x03 |
| Number of bytes | 1 byte | 2* number of registers |
| Data | Number of registers *2 bytes | |
| CRC check | 2 bytes | |

06 function code
Request:

| | | |
|------------------|---------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | 0x06 |
| Register address | 2 bytes | 0x0000-0xFFFF |
| Register value | 2 bytes | 0x0000-0xFFFF |
| CRC check | 2 bytes | |

Respond:

| | | |
|------------------|---------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | 0x06 |
| Register address | 2 bytes | 0x0000-0xFFFF |
| Register value | 2 bytes | 0x0000-0xFFFF |
| CRC check | 2 bytes | |

0x10 function code
Request:

| | | |
|---------------------|----------------------------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | 0x10 |
| Start address | 2 bytes | 0x0000-0xFFFF |
| Number of registers | 2 bytes | 0x0001 到 0x0078 |
| Number of bytes | 1 byte | Number of registers*2 |
| Register value | Number of register*2 bytes | |
| CRC check | 2 bytes | |

Respond:

| | | |
|---------------------|---------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | 0x10 |
| Start address | 2 bytes | 0x0000-0xFFFF |
| Number of registers | 2 bytes | 0x0001 to 0x0078 |
| CRC check | 2 bytes | |

2. Communication Setting

(1) **Communication baud rate: 1200, 2400, 4800, 9600, 19200 for option.**

(2) **Check Digit: None parity, odd parity, even parity.**

(3) **Byte structure: 1 start bit + 8 data bits + 1 check parity bit + 1 stop bit**

(4) **Bit sequence sending order: The least significant bit (LSB)..... The most significant bit (MSB)**

| | | | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|-------|------|
| Start | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | Check | Stop |
|-------|---|---|---|---|---|---|---|---|-------|------|

(5) **Data transferring format:**

Integer (2 bytes):

Data: (High bit) The second byte The first byte (Low bit)

Send: The second byte The first byte

For example: 1234H send 12H 34H

Floating-point type (4 bytes):

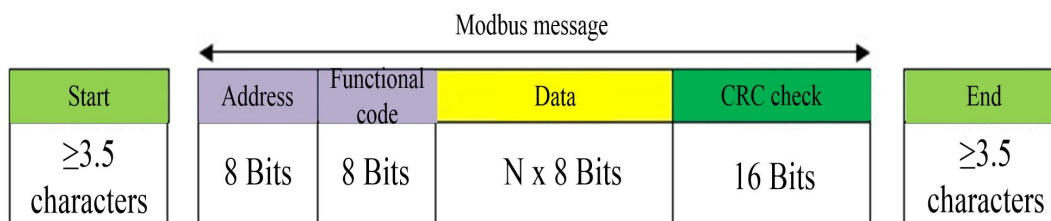
Data: (High bit) The fourth byte The third byte The second byte The first byte (Low bit)

Send: The fourth byte The third byte The second byte The first byte

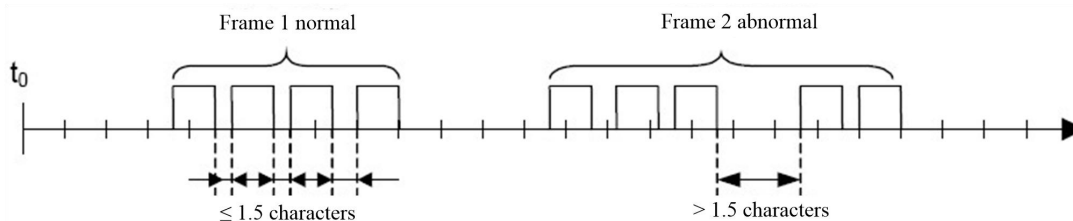
For example: 8.9 send 41H 0EH 66H 66H

3. MODBUS Message RTU Frame Format

In RTU mode, the message frames are distinguished by idle intervals with a duration of at least 3.5 characters. As the follow picture:



The entire message frame must be sent in a continuous stream of characters. If the idle space between two characters is greater than 1.5 character times, the message frame is considered as incomplete, should be discarded by receiving node. As below:



4. Abnormal Response

When host sends request data, the slave receives data abnormal, it should have abnormal reaction. If the address code sent from host is wrong, there is no this address code between slaves or the data received by slave is wrong when CRC check, no abnormal code return, the host should have super response mechanism.

Function code domain: Abnormal response function code is normal response function code +80H.

Data domain: Return to abnormal code, define as below:

Frame format returned by exception code

| | | |
|------------------|---------|--------------------------------|
| Slave address | 1 byte | Pump setting address 1-32 or 0 |
| Function code | 1 byte | Host sends function code+0x80 |
| Error code types | 1 byte | As below chart |
| CRC check | 2 bytes | |

Chart 1: Abnormal code definition

| Code | Name | Meaning |
|------|--------------------------------------|---|
| 01H | Illegal function code | The function code received by peristaltic pump except 03H/06H/10H. |
| 02H | Illegal data address | This abnormal code means the register address is not allowed data which received by peristaltic pump. |
| 03H | Illegal data value | Written data does not meet the operating range. |
| 04H | Parameter error | The calculated parameters of the operation are out of range. |
| 05H | No permission obtained | When the third level permission is enabled and the current login user does not have communication permission |
| 06H | Slave device (peristaltic pump) busy | The current state of the peristaltic pump conflict with the command received, unable to complete the command. |

Peristaltic Pump only receive MODBUS command with the Main Interface, other interface do not receive message.

5. Holding Register Address and Contents

Basic Parameters Setting

| Parameter type | Address (Decimal) | Name | Range | Function code | Data Type |
|--|-------------------|--------------------|---|---------------|------------------------------|
| The following register parameters are readable and writable. | | | | | |
| Basic parameters | 1000 | Pump head model | Corresponding parameters are shown in Table 1 | 06 | unsigned short int (2 Bytes) |
| | 1001 | Tubing model | | 06 | unsigned short int (2 Bytes) |
| Transmission parameter | 1002 | Motor speed | 0.1-600 rpm | 10 | Float (4 Bytes) |
| | 1004 | Flow rate | 0.1-99999 mL/min | 10 | Float (4 Bytes) |
| | 1006 (only read) | Unit of flow rate | 0: uL/min; 1: mL/min; 2: L/min; | 03 | unsigned short int (2 Bytes) |
| Controlling parameter | 1007 | Suck-back angle | 0-360° | 06 | unsigned short int (2 Bytes) |
| | 1008 | Start/stop control | 1: Start 0: Stop | 06 | unsigned short int (2 Bytes) |
| | 1009 | Direction control | 1: Clockwise 0: Counterclockwise | 06 | unsigned short int (2 Bytes) |

| | | | | | |
|--|------|-----------------------|---|----|---------------------------------|
| | 1010 | Full speed running | 1: Start up full speed 0: Stop full speed | 06 | unsigned short int (2 Bytes) |
| | 1011 | Automatic restart | 1: Turn on 0: Turn off | 06 | unsigned short int (2 Bytes) |
| | 1012 | Operation modes | 0: Transmission 1: Dispensing | 06 | unsigned short int (2 Bytes) |
| | 1013 | Dispensing mode | 0: Dispensing 1: Fixed volume 2: Speed dispensing | 06 | unsigned short int (2 Bytes) |
| Dispensing register parameters are readable and writable | | | | | |
| Dispensing parameter | 1020 | Set liquid volume | 0.1-9999 (Accurate to 1 decimal place) | 10 | Float (4 Bytes) |
| | 1022 | Unit of liquid volume | 0: uL; 1: mL; 2: L; | 06 | unsigned short int (2 Bytes) |
| | 1023 | Operation time | 0.1-9999 (Accurate to 1 decimal place) | 10 | Float (4 Bytes) |
| | 1025 | Operation time unit | 0: sec; 1: min; 2: hour; | 06 | unsigned short int (2 Bytes) |
| | 1026 | Pause time | 0.1-9999 (The minimum is 0.5 seconds) | 10 | Float (4 Bytes) |
| | 1028 | Pause time unit | 0: sec; 1: min; 2: hour; | 06 | unsigned short int (2 Bytes) |
| | 1029 | Repeat times | 0-9999 (0 is unlimited) | 06 | unsigned short int (2 Bytes) |
| The quantitative metering register parameters are readable and writable. | | | | | |
| Fixed volume parameters | 1030 | Set liquid volume | 0.1-9999 (Accurate to 1 decimal place) | 10 | Float (4 Bytes) |
| | 1032 | Liquid volume unit | 0: uL; 1: mL; 2: L; | 06 | unsigned short int (2 Bytes) |
| | 1033 | Set flow rate | 0.1-9999 (Accurate to 1 decimal place) | 10 | Float (4 Bytes) |
| | 1035 | Flow rate unit | 0: uL/min; 1: mL/min; 2: L/min; | 06 | unsigned short int (2 Bytes) |
| | 1036 | Pause time | 0.1-9999 | 10 | Float (4 Bytes) |
| | 1038 | Pause time unit | 0:sec; 1: min; 2: hour; | 06 | unsigned short int (2 Bytes) |
| | 1039 | Repeat times | 0-9999 (0 is unlimited) | 06 | unsigned short int (2 Bytes) |

| The dispensing speed register parameters are readable and writable. | | | | | |
|---|------|---|--|----|------------------------------|
| Dispensing speed parameter | 1040 | Motor speed | 0.1-600rpm | 10 | Float (4 Bytes) |
| | 1043 | Operation time | 0.1-9999 (Accurate to 1 decimal place) | 10 | Float (4 Bytes) |
| | 1045 | Operation time unit | 0: sec; 1: min; 2: hour; | 06 | unsigned short int (2 Bytes) |
| | 1046 | Pause time | 0.1-9999 | 10 | Float (4 Bytes) |
| | 1048 | Pause time unit | 0: sec; 1: min; 2: hour; | 06 | unsigned short int (2 Bytes) |
| | 1049 | Repeat times | 0-9999 (0 is unlimited) | 06 | unsigned short int (2 Bytes) |
| Calibration parameters can only be written, not read. | | | | | |
| Calibration parameter | 2000 | Reset | 1: Reset | 06 | unsigned short int (2 Bytes) |
| | 2003 | Start up calibration | 1: Start 0: Stop | 06 | unsigned short int (2 Bytes) |
| | 2004 | Actual filling volume | 0.01-9999.99mL | 10 | Float (4 Bytes) |
| | 2008 | Fine tune to increase the liquid volume value | 0.01-9999.99mL (Cannot exceed the set liquid volume value) | 10 | Float (4 Bytes) |
| | 2010 | Fine tune to decrease the liquid volume value | 0.01-9999.99mL (Cannot exceed the set liquid volume value) | 10 | Float (4 Bytes) |
| The following register parameters can only be read | | | | | |
| | 3000 | Total amount of transmission | 0-9999990mL | 03 | Float (4 Bytes) |
| | 3001 | Total transfer time | 0-3599996400sec | 03 | Float (4 Bytes) |

Note:

- 1) When the pump head and hose model are modified, all current parameters will be recalculated. In order to ensure the correct parameters, it is recommended to reset the function parameters to be used.
- 2) When external analog speed control is turned on, registers 1002 and 1004 cannot set parameters.
When you need to change from the transmission mode to the [Fixed volume] mode, you first need to set the operation mode (1012) value to 1, and then set the distribution mode (1013) value to 1 (the same applies to the dispensing and speed dispensing settings).
- 3) When modifying the [Dispensing], [Fixed volume], and [Speed dispensing] parameters, if the parameters sent exceed

the current pump head range, an error prompt will not be returned immediately. All parameters will be recalculated when starting. If there is an error, an exception code 04H will be returned.

- 4) Please set the register parameters individually according to the table. Do not accept a single instruction to set multiple registers continuously.
- 5) Some calibration parameters are only available in the stopped state.

Table 1 Pump head and tubing No.

Pump head and tubing chart:

| Pump head | Pump head model | Tubing model | Tubing specification |
|-------------|-----------------|--------------|----------------------|
| EasyPumpI | 0 | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| | | 25 | 25# |
| | | 17 | 17# |
| | | 18 | 18# |
| EasyPumpII | 1 | 15 | 15# |
| | | 24 | 24# |
| | | 35 | 35# |
| | | 36 | 36# |
| EasyPumpIII | 2 | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| | | 25 | 25# |
| | | 17 | 17# |
| | | 18 | 18# |
| EasyPumpIV | 3 | 15 | 15# |
| | | 24 | 24# |
| | | 35 | 35# |
| | | 36 | 36# |
| EasyPumpV | 4 | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| | | 25 | 25# |
| EasyPumpVI | 5 | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |

| | | | |
|---------------|----|-----|---------|
| | | 16 | 16# |
| | | 25 | 25# |
| 2*EasyPumpI | 6 | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| | | 25 | 25# |
| | | 17 | 17# |
| 2*EasyPumpII | 7 | 15 | 15# |
| | | 24 | 24# |
| | | 35 | 35# |
| | | 36 | 36# |
| 2*EasyPumpIII | 8 | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| | | 25 | 25# |
| | | 17 | 17# |
| 2*EasyPumpIV | 9 | 15 | 15# |
| | | 24 | 24# |
| | | 35 | 35# |
| | | 36 | 36# |
| EasyPumpV-Y | 10 | 115 | 0.5*1.6 |
| | | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| EasyPumpVI_Y | 11 | 115 | 0.5*1.6 |
| | | 13 | 13# |
| | | 14 | 14# |
| | | 19 | 19# |
| | | 16 | 16# |
| DZ25-3L | 16 | 15 | 15# |
| | | 24 | 24# |
| | | 35 | 35# |
| | | 36 | 36# |

| | | | |
|-----------|----|-----|-----------|
| 2*DZ25-3L | 17 | 15 | 15# |
| | | 24 | 24# |
| | | 35 | 35# |
| | | 36 | 36# |
| AMC_(10) | 25 | 101 | 1*1 |
| | | 102 | 2*1 |
| | | 103 | 2.4*0.86 |
| | | 104 | 2.79*0.86 |
| | | 105 | 3*1 |
| | | 106 | 0.19*0.86 |
| | | 107 | 0.25*0.86 |
| | | 108 | 0.51*0.86 |
| | | 109 | 0.89*0.86 |
| | | 110 | 1.14*0.86 |
| | | 111 | 1.42*0.86 |
| | | 112 | 2.06*0.86 |
| AMC_(6) | 26 | 101 | 1*1 |
| | | 102 | 2*1 |
| | | 103 | 2.4*0.86 |
| | | 104 | 2.79*0.86 |
| | | 105 | 3*1 |
| | | 106 | 0.19*0.86 |
| | | 107 | 0.25*0.86 |
| | | 108 | 0.51*0.86 |
| | | 109 | 0.89*0.86 |
| | | 110 | 1.14*0.86 |
| | | 111 | 1.42*0.86 |
| | | 112 | 2.06*0.86 |
| | | 114 | 0.13*0.86 |

6. Sending Data Format

Unsigned short int format

| Peristaltic pump address | Function code | Register address | | Data (unsigned short int) | | CRC | |
|--------------------------|---------------|------------------|-----------|---------------------------|--------|-----|---|
| | | Address H | Address L | Data H | Data L | L | H |
| | 06H | | | | | | |

Float format

| Pump address | Function code | Register address | | The quantity of register | | The quantity of byte | Data (Float) | | | | CRC check | |
|--------------|---------------|------------------|---|--------------------------|-----|----------------------|--------------|----|----|----|-----------|---|
| | | H | L | 00H | 02H | | 04H | H2 | H1 | L2 | L1 | L |
| | 10H | H | L | 00H | 02H | 04H | H2 | H1 | L2 | L1 | L | H |

Read register format

| Peristaltic pump address | Function code | Register start address | | The number of registers | | CRC Check | |
|--------------------------|---------------|------------------------|-----------|-------------------------|--------|-----------|---|
| | | Address H | Address L | Data H | Data L | L | H |
| | 03H | Address H | Address L | Data H | Data L | L | H |

(1) Set pump head model

The peristaltic pump address is 1, set the pump head to EasyPump, the number is 0000H.

Send: **01 06 03 E8 00 00 09 BA**

Back: **01 06 03 E8 00 00 09 BA**

(2) Set tubing model

The peristaltic pump address is 1, set the tubing model to 16#, the number is 0010H

Send: **01 06 03 E9 00 10 59 B6**

Back: **01 06 03 E9 00 10 59 B6**

(3) Set motor speed

The peristaltic pump address is 1, set the motor speed to 58.8rpm.

Send: **01 10 03 EA 00 02 04 42 6B 33 33 58 29**

Back: **01 10 03 EA 00 02 60 78**

(4) Set flow rate

The peristaltic pump address is 1, set the flow rate to 50ml/min

Send: **01 10 03 EC 00 02 04 42 48 00 00 7D 2C**

Back: **01 10 03 EC 00 02 80 79**

(5) Set back suction angle

The peristaltic pump address is 1, set back suction angle to 60°.

Send: **01 06 03 EF 00 3C B8 6A**

Back: **01 06 03 EF 00 3C B8 6A**

(6) Start/stop control

The peristaltic pump address is 1, controlling start is 0001H, controlling stop is 0000H

Send start: **01 06 03 F0 00 01 48 7D**

Back: **01 06 03 F0 00 01 48 7D**

Send stop: **01 06 03 F0 00 00 89 BD**

Back: **01 06 03 F0 00 00 89 BD**

(7) Direction control

The peristaltic pump address is 1, clockwise is 0001H, counterclockwise is 0000H.

Send: **01 06 03 F1 00 01 19 BD (clockwise)**

Back: **01 06 03 F1 00 01 19 BD**

(8) Set full speed

The peristaltic pump address is 1, full speed is 0001H

Send: **01 06 03 F2 00 01 E9 BD**

Back: **01 06 03 F2 00 01 E9 BD**

(9) Set operation mode

The peristaltic pump address is 1, set operation mode to dispensing mode

Send: **01 06 03 F4 00 01 09 BC**

Back: **01 06 03 F4 00 01 09 BC**

(10) Set allocation mode

The peristaltic pump address is 1, set allocation mode is dispensing mode

Send: **01 06 03 F5 00 00 99 BC**

Back: **01 06 03 F5 00 00 99 BC**

(11) Set the timed quantitative liquid volume

The peristaltic pump address is 1, set liquid volume to 10.00mL

Liquid volume value (register 1020) Send: **01 10 03 FC 00 02 04 41 20 00 00 FD B8**

Back: **01 10 03 FC 00 02 81 BC**

Liquid volume units (register 1022) Send: **01 06 03 FE 00 01 29 BE**

Back: **01 06 03 FE 00 01 29 BE**

(12) Set the timing and quantitative running time

The peristaltic pump address is 1, set operation time to 10.00s

Time value (register 1023) Send: **01 10 03 FF 00 02 04 41 20 00 00 BD AD**

Back: **01 10 03 FF 00 02 71 BC**

Time value unit (register 1025) Send: **01 06 04 01 00 00 D9 3A**

Back: **01 06 04 01 00 00 D9 3A**

(13) Set pause time of Dispensing

The peristaltic pump address is 1, set pause time to 1s

Pause time (register 1026) Send: **01 10 04 02 00 02 04 3F 80 00 00 4D 4A**

Back: **01 10 04 02 00 02 E1 38**

Pause time unit (register 1028) Send: **01 06 04 04 00 00 C9 3B**

Back: **01 06 04 04 00 00 C9 3B**

(14) Set the number of repetitions of the Dispensing (register 1029)

The peristaltic pump address is 1, set the number of repetitions to 100

Send: **01 06 04 05 00 64 99 10**

Back: **01 06 04 05 00 64 99 10**

7. Appendix 1—CRC Check C Language Code

CRC generation process:

- (1) Put one 16 bits register into hexadecimal FFFF(all 1), we call it CRC register.
- (2) Make the first 8 bytes with 16 CRC register low bytes XOR, the result put in CRC register.
- (3) Detect LSB of CRC register

If LSB is 0, move CRC register 1 bit to right (towards to direction of LSB) , MSB zeroing.

If LSB is 1, move CRC register 1 bit to right (towards to direction of LSB), MSB zeroing, then XOR the polynomial

value of the CRC register 0xA001 (1010 0000 0000 0001).

- (4) Repeat Step 3, until finish 8 shifts. After finish this operation, will finish the complete operation for 8 Bytes.
- (5) Repeat Step 2 to Step 5 for the next Bytes in message. Continue this operation till all the message be deal with finished.
- (6) The final content in CRC register is CRC value.
- (7) When put CRC value in message, high and low Bytes must be exchanged, described as below:

C language code:

```
void CRCVerify(char *rec,char CRClen,char CRCdata[2])
{
    char i1,j;
    unsigned int crc_data=0xffff;
    for(i1=0; i1<CRClen; i1++)
    {
        crc_data=crc_data^rec[i1];
        for(j=0; j<8; j++)
        {
            if(crc_data&0x0001)
            {
                crc_data>>=1;
                crc_data^=0xA001;
            }
            else
            {
                crc_data>>=1;
            }
        }
    }
    CRCdata[0]=(char)(crc_data);
    CRCdata[1]=(char)(crc_data>>8);
}
```