

# **PL-D753**

# CMOS | SONY IMX421 | HDR MODEL

The Pixelink PL-D753 camera model with the Sony IMX421 3rd generation Pregius CMOS global shutter sensor is ideal for high dynamic range imaging applications requiring both high resolution images and fast frame rates. Available in mono and color, the IMX421 performs well in the NIR range.

HDR imaging is a technique used to render a captured image with a greater dynamic range of luminosity than is possible with standard digital imaging. A key feature of the IMX421 Sony sensor is a Dual ADC mode where each pixel can be read out with two different gains when enabled.

The PL-D753 combines the Dual ADC images into a single hybrid HDR image, directly on camera - thus removing the need for any host processing. Real time on camera HDR is an easy way for the user to gain 6-10dB of additional dynamic range on their image without straining the CPU or requiring additional complex software algorithms.

As with all the Pixelink cameras, the PL-D753 is compatible with Pixelink Capture, our free real-time interactive multi-camera software application.



## TYPICAL APPLICATIONS

High Speed Inspection Security Real-time Sports Analysis Medical Imaging PCB Inspection

# **KEY FEATURES**

























### **TECHNICAL SPECIFICATIONS**

SensorSony IMX421TypeCMOS Global ShutterResolution2.8MP (1936 x 1464)Pixel Pitch4.5 μm x 4.5 μmActive Area11 mm diagonal

#### PERFORMANCE SPECIFICATIONS

FPN < 0.03% of signal
PRNU < 0.4% of signal
Dynamic Range 72 dB
Bit Depth 8 or 12-bit
Color Data Formats Bayer 8, Bayer 12 Packed, Bayer 16 & YUV422
Mono Data Formats Mono 8, Mono 12 Packed & Mono 16

#### FRAME RATES

 Resolution
 Free Running

 1936 x 1464
 141.1 fps

 1280 x 1024
 203 fps

 640 x 480
 403.8 fps

Frame rates will vary based on host system and configuration \*Above calculations based on fixed frame rate mode

#### **INTERFACES**

Interface | Date rate USB 3.0 | Micro-B | 5Gbps Board Level Trigger 8-pin Molex 1.25mm pitch Connector

Enclosed Trigger Hirose round 8-pin

Connector

Trigger Software and hardware Board Level Trigger 1 input, 3.3V (with internal

Input
Enclosed Trigger Input

pullup resistor)
1 optically Isolated,

5-12V DC at 4-11 mA Board Level GPO/Strobe 2 outputs, 3.3V

Enclosed GPO/Strobe 2 outputs, 3.3V and 1 optically isolated max 40V DC, max 15mA

GPI 1 input, 3.3V (with internal

pullup resistor)

#### **MECHANICALS**

Dimensions (mm) 55 x 38.5 x 30.29

Weight (g) 35.8 (Board level without optics)

Mounting C-Mount

#### **POWER REQUIREMENTS**

Voltage Required 5V DC (from USB connector)

#### PIN NAME & FUNCTION

3.3V power output
 TRIGGER/GPI 3.3V HCMOS input

3 Ground

4 GPO1, 3.3V HCMOS output

5 GPO2, 3.3V HCMOS output

Clock, 3.3V (I2C access for OEMs)Data, 3.3V (I2C access for OEMs)

8 No connection

Board connector: Molex (8-pin, 1.25mm pitch, vertical); Cable receptacle: Molex 51021-0800; Cable crimp terminals: Molex 50079-8100

#### **ENCLOSED GPIO INTERFACE PIN OUTPUT DESCRIPTION**

1 VBUS (Power output from USB 3.0 cable)

2 TRIGGER + (optically isolated)

3 TRIGGER - (optically isolated)

4 GPO1 + (optically isolated)
 5 GPO1 - (optically isolated)

6 GPO1, 3.3V HCMOS output (I2C - SCL for autofocus)

7 GPO2, 3.3V HCMOS output (I2C - SDA for autofocus)

8 Ground (logic and chassis ground)

#### **ENVIRONMENTAL & REGULATORY**

Compliance FCC, CE & RoHS
Shock & Vibration 300 G & 20 G (10Hz - 2KHz)
Operating Temperature 0°C to 50°C
Storage Temperature -45°C to 85°C

### **SOFTWARE**

Pixelink Capture Control & operate multi-camera
Pixelink SDK Software Development Kit
Pixelink µScope Acquisition, analysis & reporting

3rd. Party U3V Vision Applications

### **COMPUTER & OPERATING SYSTEM**

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	Windows	Linux x86	Linux ArmV7	Linux ArmV8			
Processor	Intel i5 or better	Intel i5 or better	Arm7 (32 bit)	Arm8 (64 bit)			
Memory	4GB recommended	4GB recommended	2GB	2GB			
Hard Drive Space	150 MB	150 MB	50 MB	50 MB			

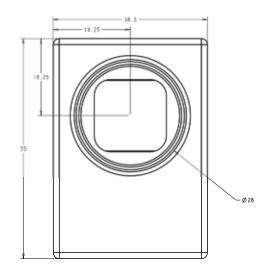
Operating Windows Ubuntu Ubuntu Ubuntu System 7/8/10 Ubuntu Ubuntu Ubuntu 14.04/16.04 14.04/16.04 14.04/16.04 Desktop

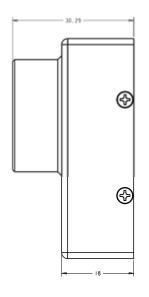


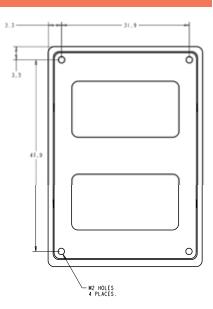
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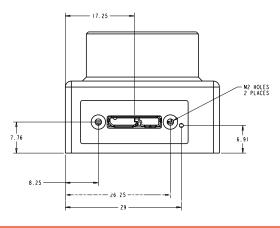
# MECHANICAL DRAWINGS & RESPONSIVITY CURVES

### MECHANICAL DRAWINGS

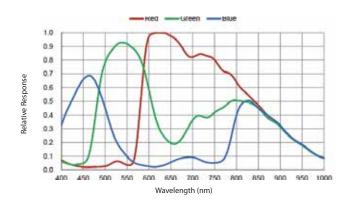




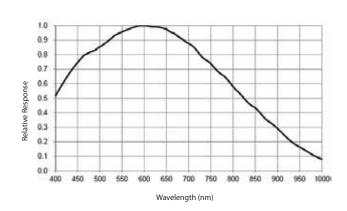




### **RESPONSIVITY CURVE - COLOR**



### **RESPONSIVITY CURVE - MONO**





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# PIXELINK'S INDUSTRY LEADING SOFTWARE

#### PIXELINK CAPTURE

Pixelink Capture is powerful multi-camera software application designed to configure "n" numbers of cameras and stream "n" number of cameras simultaneously in real-time high-quality video viewed in a multi-window environment. Pixelink Capture offers options for complex image enhancements such as; exposure control, filtering, frame-by-frame property changes in addition to multi-camera application testing and configuration.

Pixelink Capture also provides features to measure supporting; point, line, circle, rectangle, polyline and polygon measurements while determining pixel location. After creating spatial calibration, the user can review and adjust before exporting the findings to an Excel spreadsheet for further analysis. Pixelink Capture also has integrated lens control (zoom & focus) for Navitar motorized lenses and accurate autofocus options for Navitar motorized fine focus mechanisms.

Visit pixelink.com for more detailed information.

#### PIXELINK SDK

Providing full control of all camera functions, the Pixelink Software Developers Kit (SDK) is the software package of choice for developers and system integrators who are integrating Pixelink cameras into their applications. The Pixelink SDK provides access to the full Pixelink Application Programming Interface (API) and provides sample applications, wrappers for many 3rd party controls, such as LabVIEW, along with full documentation.

The Pixelink SDK is compatible with Microsoft Windows and popular Linux platforms. When using the Pixelink SDK, developers can integrate Pixelink cameras into their custom applications with ease.

### **AVAILABLE CONFIGURATIONS**

 PL-D753CU
 PL-D753MU

 PL-D753CU-BL
 PL-D753MU-BL

 PL-D753CU-T
 PL-D753MU-T

Color Space C = Color M = Mono NIR = Near Infrared Interface F = Firewire G = GigE U = USB

Housing CS = CS Mount S-BL = S Mount Board Level

BL = Board Level T = Trigger

